

This is the Revision A version of the [Bench RoboBrick](#). The status of this project is [abandoned](#).

Bench Robobrick (Revision A)

Table of Contents

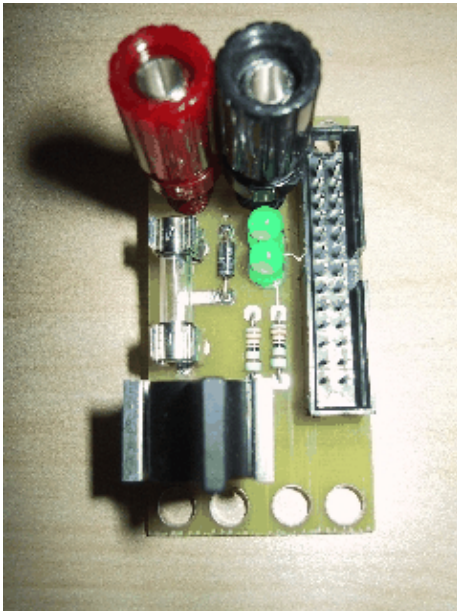
This document is also available in [PDF](#) format.

- [1. Introduction](#)
- [2. Hardware](#)
 - ◆ [2.1 Circuit Schematic](#)
 - ◆ [2.2 Printed Circuit Board](#)
- [3. Issues](#)

1. Introduction

The Bench RoboBrick provides a way of connected a bench power supply to a RoboBrick Hub module to power all of the RoboBricks.

A picture of the Bench–A RoboBrick is shown below:

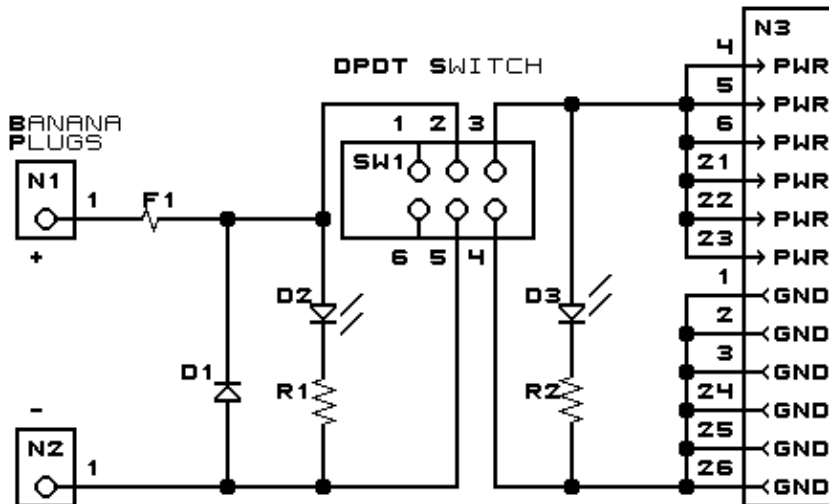


2. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

2.1 Circuit Schematic

The schematic for the Bench RoboBrick is shown below:



BENCH ROBOBRICK MODULE (REV. A)
 COPYRIGHT (C) 2000 -- WAYNE C. GRAMLICH

The parts list kept in a separate file -- [bench.ptl](#).

2.2 Printed Circuit Board

The printed circuit board files are listed below:

[bench_back.png](#)

The solder side layer.

[bench_front.png](#)

The component side layer.

[bench_artwork.png](#)

The artwork layer.

[bench.gbl](#)

The RS-274X "Gerber" back (solder side) layer.

[bench.gtl](#)

The RS-274X "Gerber" top (component side) layer.

[bench.gal](#)

The RS-274X "Gerber" artwork layer.

[bench.drl](#)

The "Excellon" NC drill file.

[bench.tol](#)

The "Excellon" tool rack file.

3. Issues

After the boards have been manufactured, assembled, and tests, there are usually a number of issues that come and need to be recorded. This section of the document is reserved for those issues.

[Copyright](#) (c) 2000–2002 by [Wayne C. Gramlich](#). All rights reserved.