This is the Revision A verion of the <u>In8 RoboBrick</u>. The status of this project is that it has been <u>replaced</u> by the <u>InOut10 RoboBrick</u>.

In8 Robobrick (Revision A)

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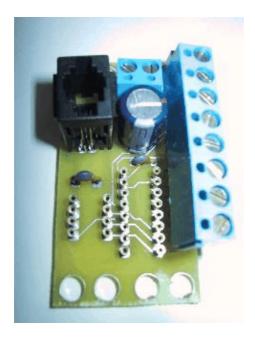
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1. Introduction

The In8 RoboBrick allows you to read up to 8 digital inputs. An interrupt can be generated on the states of selected inptus.

A picture of the In8-A RoboBrick is shown below:



2. Programming

The basic operation is to send a query to the In8 RoboBrick to read the 4 bits of data. The programmer can download a complement mask to cause any of the bits to be complemented prior to reading.

The In8 RoboBrick supports <u>RoboBrick Interrupt Protocol</u>. The interrupt pending bit is set whenever the the formula:

$$L\&(\sim I) \mid H\&I \mid R\&(\sim P)\&I \mid F\&P\&(\sim I)$$

is non-zero, where:

- I is the current input bits XOR'ed with the complement mask (C)
- P is the previous value of I
- L is the low mask
- H is the high mask
- R is the raising mask
- F is the falling mask

and

- ~ is bit—wise complement
- | is bit-wise OR
- & is bit-wise AND

Once the interrupt pending bit is set, it must be explicitly cleared by the user.

The In8 RoboBrick supports both the standard shared commands and the shared interrupt commands in addition to the following commands:

Command	Send/	Byte Value								Discussion
	Receive	7	6	5	4	3	2	1	0	Discussion
Read Inputs									0	Return input values abcdefgh (after XOR'ing
	Receive	a	b	c	d	e	f	g	h	with complement mask)
Read Complement Mask	Send	0	0	0	0	0	0	0	1	Return complement mask ccccccc
	Receive	c	c	c	c	c	c	c	c	
Read Low Mask	Send	0	0	0	0	0	0	1	0	Return low mask <i>llllllll</i>
	Receive	l	l	l	l	l	l	l	l	
Read High Mask	Send	0	0	0	0	0	0	1	1	Return high mask hhhhhhhhh
	Receive	h	h	h	h	h	h	h	h	
Read Raising Mask	Send	0	0	0	0	0	1	0	0	Return raising mask rrrrrrr
	Receive	r	r	r	r	r	r	r	r	
Read Falling Mask	Send	0	0	0	0	0	1	0	1	Return falling mask ffffffff
	Receive	f	f	f	f	f	f	f	f	
Read Raw										Return raw data abcd (without XOR'ing with
	Receive	a	b	c	d	e	f	g	h	complement mask)
Set Complement Mask					0					Set complement mask to ccccccc
	Send	c	c	c	С	c	c	c	С	
Set Low Mask	Send	0	0	0	0	1	0	1	0	Set low mask to IllIllII
	Send	l	l	l	l	l	l	l	l	Det 10w mask to mum
Set High Mask	Send	0	0	0	0	1	0	1	1	Set high mask to hhhhhhhhh

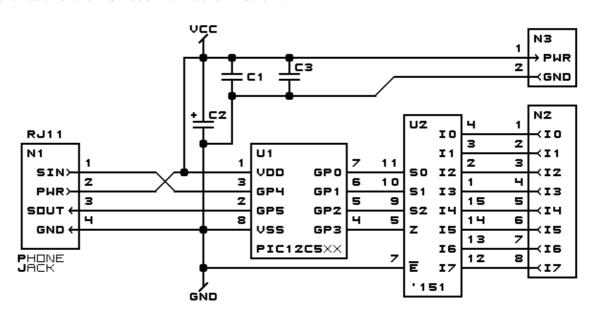
					h					
Set Raising Mask	Send	0	0	0	0	1	1	0	0	Set raising mask to rrrrrrr
	Send	r	r	r	r	r	r	r	r	
Set Falling Mask	Send	0	0	0	0	1	1	0	1	Set falling mask to ffffffff
	Send	f	f	f	f	f	f	f	f	
Read Interrupt Bits	Send	1	1	1	0	1	1	1		Return the interrupt pending bit p and the interrupt enable bit e .
	Receive	0	0	0	0	0	0	e	p	
Set Interrupt Commands	Send	1	1	1	1	0	c	c	c	Set Interrupt Command ccc.
Shared Commands	Send	1	1	1	1	1	c	c	c	Execute Shared Command ccc.

3. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

3.1 Circuit Schematic

The schematic for the In8 RoboBrick is shown below:



```
INS ROBOBRICK MODULE (REV. A)
COPYRIGHT (C) 2000 -- WAYNE C. GRAMLICH
```

The parts list kept in a separate file $--\underline{\text{in 8.ptl}}$.

3.2 Printed Circuit Board

The printed circuit board files are listed below:

in8 back.png

The solder side layer.

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in8 front.png

The component side layer.

in8 artwork.png

x The artwork layer.

in8.gbl

The RS-274X "Gerber" back (solder side) layer.

in8.gtl

The RS-274X "Gerber" top (component side) layer.

in8.gal

The RS-274X "Gerber" artwork layer.

in8.drl

The "Excellon" NC drill file.

in8.tol

The "Excellon" tool rack file.

4. Software

The In8 software is available as one of:

in8.ucl

The µCL source file.

in8.asm

The resulting human readable PIC assembly file.

<u>in8.lst</u>

The resulting human readable PIC listing file.

in8.hex

The resulting Intel[®] Hex file that can be fed into a PIC12C5xx programmer.

In addition, there is a test suite available as:

in8 test.ucl

The µCL source file.

in8 test.asm

The resulting human readable PIC assembly file.

in8 test.lst

The resulting human readable PIC listing file.

in8 test.hex

The resulting Intel[®] Hex file that can be fed into a PIC12C5xx programmer.

5. Issues

The following issues have come up:

- The 2200 µF capacitor does not fit between the RJ11 and the terminal strip.
- One of the traces has an unnecessary kink in it.
- The 8-pin terminal strip is too close to the the 74LS151.
- The terminal strip holes are too small.
- The Lego holes are not right.
- The RJ11 holes are not right.
- We need to switch over to a 6-wire RJ11 connector.

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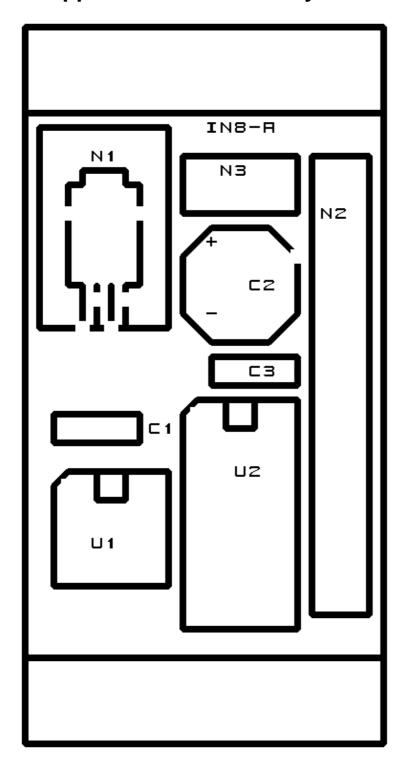
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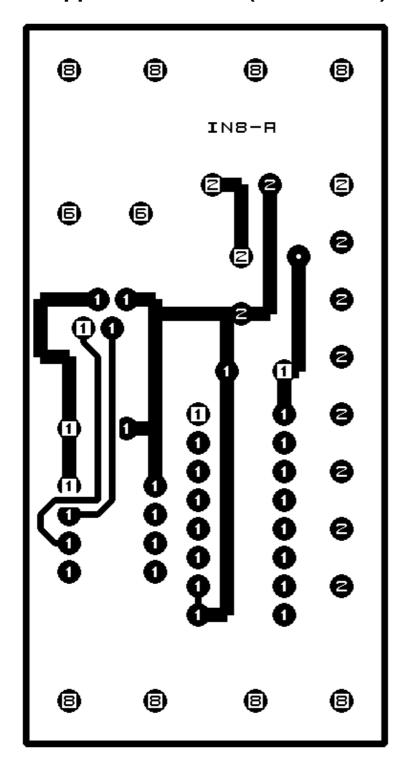
A. Appendix A: Parts List

```
# Parts list for In8 RoboBrick (Rev. A)
#
C1: Capacitor10pF - 10 pF Ceramic Capacitor [Jameco: 15333]
C2: Capacitor2200uF - 2200 uF 6.3V Electrolytic Capacitor [Jameco: 133145]
C3: Capacitor10pF - 10 pF Ceramic Capacitor [Jameco: 15333]
N1: RJ11Female4_4.RBSlave - Female RJ11 (4-4) Phone Jack [Digikey: A9071-ND]
N2: TerminalStrip8_In8 - 8 Junction Terminal Strip [4 Jameco: 189675]
N3: TerminalStrip2.In8 - 2 Junction Terminal Strip [Jameco: 189675]
U1: PIC12C509.In8 - Microchip PIC12C509 [Digikey: PIC12C509A-04/P-ND]
U2: 74HCT151 - 8 to 1 Selector [Digikey: CD74HCT151E]
```

B. Appendix B: Artwork Layer



C. Appendix C: Back (Solder Side) Layer



D. Appendix D: Front (Component Side) Layer

