This is the Revision B verion of the Laser1 RoboBrick. The status of this project is work in progress.

LaserHead1 Robobrick (Revision B)

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1. Introduction

The LaserHead1 RoboBrick is a module that is designed to hold a slightly modified laser pointer and four photo detectors for the Laser1 RoboBrick.

It has a central hole which the laser shines through. Around the hole are four photo detectors. In addition, there are four screw holes that can be used to mount the light shield bracket and the laser pointer bracket. There is a connector that is used to power the laser and read back the photo detector voltage.

2. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

2.1 Circuit Schematic

The schematic for the LaserHead1 RoboBrick is shown below:



The parts list kept in a separate file --<u>laserhead1.ptl</u>.

2.2 Printed Circuit Board

The printed circuit board files are listed below:

```
laserhead1 back.png
       The solder side layer.
laserhead1 front.png
       The component side layer.
laserhead1 artwork.png
       The artwork layer.
laserhead1.gbl
       The RS-274X "Gerber" back (solder side) layer.
laserhead1.gtl
       The RS-274X "Gerber" top (component side) layer.
laserhead1.gal
       The RS-274X "Gerber" artwork layer.
<u>laserhead1.d</u>rl
       The "Excellon" NC drill file.
laserhead1.tol
       The "Excellon" tool rack file.
```

3. Assembly Instructions

The light shield is made out of a 35mm film cannister and its lid. The bottom is cut off the film cannister using a hack saw. The lid has a hole drilled in the middle. The lid is temporarily screwed to the center hole of

the LaserHead1 board and used as a template to mark where the four screw holes need to be drilled. The lid is removed and the four mounting holes are drilled. Next, using a handheld hole punch, larger holes are cut for the photo detectors to fit through.

{There needs to be some additional plastic removed so that the soldered in detectors do not interfere with the plastic.}

The laser mounting bracket is constructed out of two 1 inch square pieces of 3/8 inch thick plastic. A cross is scribed into the square to find the center. A small guide hole is drilled in the center of both pieces. Each piece is mounted on the LaserHead1 board using a small screw. The LaserHead1 board is used a template to locate where the screw holes should be drilled. The four screw holes are drilled in each piece. The center hole of each piece is enlarged to a width just barely large enough to hold the laser pointer. Finally, one of the square pieces has a hole drilled on the side, that is tapped for a small set screw.

The photo dectectors and connector are soldered to the LaserHead1 board. The LaserHead1 is sandwiched between the 35mm lid and the two square pieces of plastic. Four screws are fed through the holes and capped with a washer, lock washer, and a nut. The laser pointer is fed into the center hole and secured in place with the set screw. The 35mm body is attached to the lid.

Two wires are attached to the laser pointer plus and minus leads and soldered to the LaserHead1 board. If you get the polarity reversed, it is quite likely that the laser pointer will die; so get it right! Use a nylon tie strip to permanently turn the laser on.

Run a cable between the Laser1 board and the LaserHead1 board. Plug the Laser1 board into a powered hub. Using a shorting block on the Laser1 board (N4), turn on the laser. Shine it at a reflector. Adjust R4 until the LED (D1) lights reliably when the laser beam hits a reflector. Disconnect the shorting block (N4). You are done.

4. Issues

Any fabrication issues are listed here.

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A. Appendix A: Parts List

Parts list for Laser1 RoboBrick (Rev. B)
#
D1-24: IRD500 - Infrared Detector [Jameco: 112168]
N1: Header1x6.LaserHead1 - 1x6 Male Header [6/40 Jameco: 160881]
N2: Header1x2.LaserHead1 - 1x2 Male Header [2/40 Jameco: 160881]



B. Appendix **B**: Artwork Layer

C. Appendix C: Back (Solder Side) Layer



D. Appendix D: Front (Component Side) Layer

