This is the Revision A verion of the <u>Line3 module</u>. The status of this project is <u>finished</u>.

# **Line3 Module (Revision A)**

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### 1. Introduction

The Line3 module has 3 infrared (IR) sensors for sensing lines on flat surfaces. There are sensor that straddle the line and one that can detect when the line simply ends.

# 2. Programming

{more goes here.}

In addition to the <u>common shared commands</u> and the <u>shared interrupt commands</u>, the Line3 RoboBrix supports following commands:

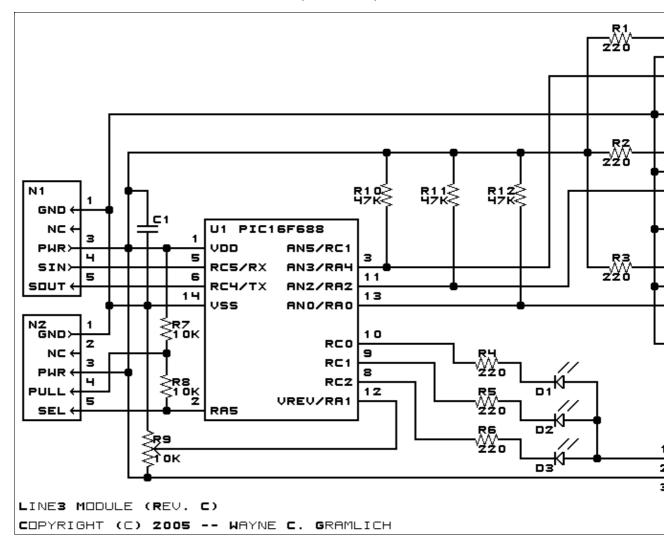
Command	Send/ Receive	Byte Value								Discussion
		7	6	5	4	3	2	1	0	Discussion
Read Interrupt Bits	Send	1	1	1	0	1	1	1	1	Return the interrupt pending bit $p$ and the interrupt enable bit $e$ .
	Receive	0	0	0	0	0	0	e	p	
Set Interrupt Commands	Send	1	1	1	1	0	c	c	c	Set Interrupt Command ccc.
Shared Commands	Send	1	1	1	1	1	c	c	c	Execute common shared command ccc

# 3. Hardware

The hardware consists of a circuit schematic and a printed circuit board.

#### 3.1 Circuit Schematic

The schematic for the Line3 RoboBrix is shown below:



The parts list kept in a separate file — <u>line3.ptl</u>.

#### 3.2 Printed Circuit Board

The printed circuit board files are listed below:

#### line3\_back.png

The solder side layer.

#### line3 front.png

The component side layer.

#### line3 artwork.png

The artwork layer.

#### line3.gbl

The RS-272X "Gerber" back (solder side) layer.

#### line3.gtl

The RS-272X "Gerber" top (component side) layer.

#### line3.gal

The RS-272X "Gerber" artwork layer.

#### line3.drl

The "Excellon" NC drill file.

3.2 Printed Circuit Board

line3.tol

The "Excellon" tool rack file.

# 4. Software

The Line3 software is available as one of:

line3.ucl

The µCL source file.

line3.asm

The resulting human readable PIC assembly file.

line3.lst

The resulting human readable PIC listing file.

<u>line3.hex</u>

The resulting Intel<sup>®</sup> Hex file.

# 5. Issues

Any fabrication iusses will be listed here.

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